I. Introduction

LATTICE sandwich structures arouse much attention in recent two decades because of their outstanding performance in stiffness, strength, energy absorption, and the multifunctional design [1–4]. When subjected to a deformation dominated by stretching, lattice sandwich structures demonstrate preferable weight-efficiency compared with bending-dominated structures such as honeycomb sandwich structures [5–7]. Various techniques can be implemented to fabricate lattice sandwich structures, such as investment casting, deformation forming, and woven metal textiles [8–10]. However, traditional manufacturing techniques cannot achieve a satisfactory precision and geometrical complexity that are oftentimes simultaneously required by satellite structures. In recent years, the development of additive manufacturing techniques, such as selective laser melting and electron beam melting, makes the high-precision lattice structures become reality [11–13]. The geometric precision of the lattice has been reduced to submillimeter scale. The deformation behavior of the lattice sandwich plate has been studied via both numerical analysis and experimental testing. It is found that multiple factors, such as the parent material, the shape and size of the cell, as well as the connectivity, can influence the mechanical properties of the lattice sandwich plate [5]. In aeronautical and aerospace applications, an increasing number of brackets based on lattice sandwich structures have been designed. However, to our best knowledge, the large-scale assembly structure such as satellite structure based on lattice sandwich structures has not been yet verified by experiments.

In this paper, a lightweight satellite structure based on lattice sandwich panels is designed. In this satellite structure all panels are manufactured from aluminum alloy AISI10Mg by direct metal laser melting. The dimensions of the structure are 400 × 400 × 400 mm³, whereas its mass and carrying capacity reach 8 and 104 kg, respectively. The structure’s weight-to–satellite weight ratio is 7.7% in comparison to the ratio about 15–25% of minisatellites (satellites with the weight in the range from 100 to 500 kg) made of traditional aluminum honeycomb sandwich panels. Results of vibration tests reveal that the satellite structure could endure vibration loads entailed by the rocket launching.

II. Design and Fabrication of the Satellite Structure

The design flow of the satellite structure made of lattice sandwich panels is as shown in Fig. 1. In the “choice of cell” process, the lattice cell of the satellite structure is chosen according to the application requirement. In the “stiffness equivalence” process, the lattice core layer is simulated with a homogeneous material layer with the equivalent stiffness. In the “satellite finite element method (FEM) model” process, the satellite structure is modeled by shell elements as well as solid elements and multi-point constraints elements. In the “satellite vibration analysis” process, the sinusoidal vibration and random vibration loads are applied to the FEM model. In the “force at joints” process, the forces at joints between panels, between equipment and panels, and between satellite and rocket are calculated. In the “design of joints” process, the joint structures are designed as solid surrounded by small cells rather than large cells to improve the local mechanical strength. The designed bearing capacity of joint structures should be larger than the force at joints calculated in the former process. In the “strength test of joints” process, the joint structures with the lattice sandwich panels are tested with testing machine. The tensile strength of the joints is obtained and verified by experiments. In the “satellite model” process, the satellite structure composed of lattice sandwich panels is built with 3D modeling software. In the “satellite fabrication” process, the satellite structure composed of lattice sandwich panels is fabricated with direct metal laser melting technique. In the “satellite vibration tests” process, the sinusoidal vibration and random vibration tests are conducted.

The superiority of the satellite structure made of lattice and its comparison with honeycomb are shown in Table 1. The satellite structure made of lattices has advantages in aspects such as stiffness, strength, connections, special-shaped structural configuration, multifunctional property, light-weight property, and fabrication cycle.

The lattice cell of the satellite structure is pyramidal, as shown in Fig. 2a. This type of cell has the advantage of low relative density and high stiffness-to-weight ratio [14]. Relative density $\bar{\rho}$ and effective elastic modulus $E_{ij}$ of this lattice type yield

$$\bar{\rho} = \frac{\rho}{\rho_0} = \left(\frac{\delta}{D}\right)^2 = \frac{\pi}{\sin^2(\alpha)} \left(\frac{\delta}{D}\right)^2$$

(1)

$$E_{ij} = E_0\bar{\rho}\sin^4(\alpha) = \frac{\sqrt{3\pi}}{\rho_0}\left(\frac{\delta}{D}\right)^2$$

(2)

where $\alpha$ is the angle between the lattice struts and the horizontal plane, $\delta$ the diameter of the strut, $D$ the dimensions of the lattice, and $E_0$ the elastic modulus of the parent material. The diameter of the lattice struts adopted in the present study is 0.5 mm, which is the minimum value that we can achieve on our current device with a permissible shape and surface quality. Lattices with even smaller diameters can also be produced but the discreteness in mechanical properties become prominent. The dimensions of the lattice cell in the present work are $5 \times 5 \times 5$ mm³ (half or third of the thickness of the
panels, called large cell) in most of the regions to acquire light weight and 2.5 × 2.5 × 2.5 mm³ (quarter or sixth of the thickness of the panels, called small cell) in local regions in the vicinity of the thread joint for the strong connection.

The lattice sandwich panels are made by the lattice core and face sheets as shown in Fig. 2. The face sheets significantly strengthened the structure and make it mechanically stable when subjected to complex loads. The thickness of both top and bottom face sheets is 0.4 mm. The thickness of the bottom panel is 15.4 mm, and that of the rest of the panels is 10.4 mm. The reason to design a bottom panel with a much greater thickness is to prevent structural failures caused by insufficient load-bearing capacity. The local region adjacent to the screw joint is designed as solid surrounded by small cells rather than uniform large cells to improve the local mechanical strength. One can notice from Fig. 2c that three horizontal panels (top panel, middle panel, and bottom panel) and one vertical panel are designed as a whole part named the main structure. Meanwhile, as shown in Figs. 2c and 2d, the four inner diaphragms and four outer panels are designed purposely as a component that can be dismountable from the main structure. The dismountable inner diaphragms and outer panels significantly facilitate the installation of the equipment inside the satellite and they can be connected to the main structure through a screw joint at the edges of each panel. The distance between neighboring joints is about 50 mm.

The satellite structure is fabricated with selective laser melting technique by using a Concept X-line 1000R equipment with the maximum forming dimensions of 630 × 400 × 500 mm³ made by the Concept Laser Company. The raw material used is AlSi10Mg powder. The elastic modulus and yield strength of standard specimens produced by the same process are measured by the uniaxial tensile test and yield 70 and 220 MPa, respectively. We choose AlSi10Mg because of its superior stiffness-to-weight ratio and heat dissipation performance compared with other metals such as titanium alloy. The 3D printing method avoids a large amount of adhesives between face sheets and core, and those around connection inserts in traditional honeycomb sandwich panels. Therefore, the stiffness-to-weight ratio of the 3D printed minisatellite structure made of lattice sandwich panels could be superior to traditional minisatellite structures made of aluminium honeycomb sandwich panels.

### Table 1 Comparison of satellite structure of the same weight made of lattice and honeycomb

<table>
<thead>
<tr>
<th></th>
<th>Satellite structure made of lattice</th>
<th>Satellite structure made of honeycomb</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stiffness</td>
<td>Excellent</td>
<td>Good</td>
</tr>
<tr>
<td>Strength</td>
<td>High strength at joint position with large concentrated force</td>
<td>Low strength at joint position with large concentrated force</td>
</tr>
<tr>
<td>Structural connections</td>
<td>Small amount and light</td>
<td>Large amount and heavy</td>
</tr>
<tr>
<td>Specially shaped structural configuration</td>
<td>Well supported</td>
<td>Poorly supported</td>
</tr>
<tr>
<td>Multifunctional property</td>
<td>Well supported</td>
<td>Poorly supported</td>
</tr>
<tr>
<td>Lightweight property</td>
<td>Excellent</td>
<td>Good</td>
</tr>
<tr>
<td>Fabrication cycle</td>
<td>Short</td>
<td>Moderate</td>
</tr>
</tbody>
</table>

After all panels are fabricated separately, the satellite is assembled by screwing steel blocks to top, middle, and bottom plates of the satellite. The block placed on each plate is 32 kg; therefore, the sum of them is 96 kg in total.

### III. Vibration Tests of the Satellite Structure

To examine the structure’s ability to endure the vibration loads resulting from the rocket launching, the vibration tests are conducted. The photographs of the vibration tests are presented in Figs. 3a and 3b. Details of sinusoidal and random vibration loads are outlined in Tables 2 and 3. It is important to note that the vibration loads are applied in X (horizontal) and Z direction (vertical) successively. The Y-direction test is omitted because by neglecting the weak anisotropy (less than 5% in strength) of the printed AlSi10Mg [15], it is justified.

### Table 2 Sine vibration loads

<table>
<thead>
<tr>
<th>Frequency</th>
<th>Magnitude (0-p)</th>
<th>Frequency</th>
<th>Magnitude (0-p)</th>
</tr>
</thead>
<tbody>
<tr>
<td>5–8 Hz</td>
<td>2.69 mm (0-p)</td>
<td>5–8 Hz</td>
<td>3.14 mm (0-p)</td>
</tr>
<tr>
<td>8–100 Hz</td>
<td>0.69 g</td>
<td>8–100 Hz</td>
<td>0.805 g</td>
</tr>
<tr>
<td>Sweep rate</td>
<td>2 Oct/min</td>
<td>Sweep rate</td>
<td>2 Oct/min</td>
</tr>
</tbody>
</table>

### Table 3 Random vibration loads

<table>
<thead>
<tr>
<th>Frequency</th>
<th>PSD</th>
<th>Frequency</th>
<th>PSD</th>
</tr>
</thead>
<tbody>
<tr>
<td>20–150</td>
<td>3 dB/Oct</td>
<td>20–150</td>
<td>3 dB/Oct</td>
</tr>
<tr>
<td>150–600</td>
<td>0.041 g²/Hz</td>
<td>150–600</td>
<td>0.053 g²/Hz</td>
</tr>
<tr>
<td>Grms</td>
<td>5.72 grms</td>
<td>Grms</td>
<td>6.50 grms</td>
</tr>
<tr>
<td>Loading time</td>
<td>2 min</td>
<td>Loading time</td>
<td>2 min</td>
</tr>
</tbody>
</table>
to consider the structure as quad symmetry and therefore the responses in $Y$ direction as identical to the $X$ direction.

The frequency of the sinusoidal vibration is increased monotonically from 5 to 100 Hz. The maximum magnitudes of the loads are 0.69 g (from 8 to 100 Hz) in the $X$ direction and 0.805 g (from 8 to 100 Hz) in the $Z$ direction. The increasing rate of the excitation is 2 octaves/minute (Oct/min); that is, the frequency of the sinusoidal vibration becomes quadruple in each minute.

The frequency of the random vibration loads ranges from 20 to 2000 Hz. The maximum power spectral density (PSD) of the random vibration loads is $0.041 \text{ g}^2/\text{Hz}$ (from 150 to 600 Hz) in the $X$ direction and $0.053 \text{ g}^2/\text{Hz}$ (from 150 to 600 Hz) in the $Z$ direction. The root mean square (grms) of the random vibration loads is 5.72 grms in the $X$ direction and 6.50 grms in the $Z$ direction. The loading time is 2 minutes for each direction.

Three acceleration sensors are glued to the satellite structure to measure the acceleration responses. The acceleration responses of the satellite structure stimulated by the sine and random vibration loads are shown in Fig. 4 and Fig. 5, respectively.
are requisite for the structure design of equipment intended to be carried by the satellite into the space. The positions of three sensors are shown in Fig. 3c: on the edge of top plate, center of middle plate, and edge of bottom plate.

IV. Results and Discussion

The acceleration response in the $X$ direction stimulated by the $X$-direction sinusoidal vibration loads is plotted in Fig. 4a. It can be seen that the acceleration response increases along with the frequency from 5 to 100 Hz. The acceleration response of the top plate is greater compared with the middle plate, while that of the middle plate is greater than the bottom plate as well. At 100 Hz, the response ratio of the top, middle, and bottom plates is about $3.4/2.0/1.0$. The peak-valued response in the $X$ direction is 3.5 g. The acceleration response in the $Z$ direction stimulated by the sinusoidal vibration loads in the $Z$ direction is plotted in Fig. 4b. It can be seen that, same as the previous case, the acceleration response increases with the frequency from 5 to 100 Hz. The acceleration response of the middle plate is greater compared with the top plate. It is because the distance between the middle sensor and the edge of middle plate is larger compared with the one occurred on the top plate. However, the maximum response in the $Z$ direction (1.1 g) is much smaller than the maximum response in the $X$ direction (3.5 g). The discrepancy between the acceleration responses in the $Z$ direction associated with three plates is much smaller, which is only about 0.2 g.

The acceleration response stimulated by the random vibration loads is plotted in Fig. 5. The RMS acceleration of the top, middle, and bottom plates is 11.2, 11.9, and 8.8 g in the $X$-direction test. In contrast, these values yield 13.80, 14.9, and 8.6 g during the $Z$-direction test. It can be seen that the acceleration response of the bottom plate is more insignificant compared with both middle and top plates.

To check whether the structure has been damaged by the vibration loads, the low-magnitude sinusoidal resonance scan was performed [15]. The theoretical basis of this method is that the structure’s stiffness change can induce the variation of the resonant frequency [16–18]. In case of critical damage, the resonant frequency decreases.

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![Fig. 6 Low-magnitude X-direction vibration response comparison before and after vibration tests: a) top plate; b) middle plate; and c) bottom plate.](image)

![Fig. 7 Low-magnitude Z-direction vibration response comparison before and after vibration tests: a) top plate; b) middle plate; and c) bottom plate.](image)
obviously. Otherwise, the resonant frequency will remain the same. According to this method, the low-magnitude sine vibration loads (0.2 g from 5 to 500 Hz, 4 Oct/min) are imposed on the structure both before and after the vibration tests clarified in Tables 2 and 3. The acceleration responses recorded by sensors under two low-magnitude sine vibrations are compared with each other. The results obtained from all three sensors are presented in Fig. 6 (X direction) and Fig. 7 (Z direction). The first-order natural frequencies in the X and Z directions are 120 and 210 Hz, respectively. It can be seen that the acceleration responses before and after high-magnitude vibration coincide with each other. Some minor mismatches in Figs. 6 and 7 may arise from the changes in the prestress state around screws between panels resulting from the assembling process. For the satellite structures made of lattice sandwich panels, the weight of the adhesives and structural insert parts used in aluminum honeycomb panels is reduced; the saved weight can increase both the face sheet thickness and the stiffness of the core layer of the sandwich panels. More than that, the whole printing of structural joint and panels instead of the traditional structural inserts with adhesives can obviously increase the stiffness of the satellite structure. Therefore, the resonant frequency of the satellite structure made of lattice sandwich panels can be significantly higher than that made of aluminum honeycomb panels of the same weight. Moreover, the lattice structures avoid the frequent shear failure of honeycomb core occurred in traditional satellites. After the vibration tests, the satellite structure was disassembled and inspected visually. In this stage, neither has any fragment been noticed to drop out from the panels nor have other damages been detected. Therefore, it is justifiable to conclude that the structure has not been damaged during the high-magnitude vibration tests. That is to say, the light-weight satellite structure made of lattice sandwich panels manufactured by the selective laser sintering technique could sustain the vibration during the rocket launching.

V. Conclusions

The light-weight satellite structure of size 400 × 400 × 400 mm³ and completely made of lattice sandwich panels was designed and fabricated by selective laser sintering technique. The structure’s weight-to-satellite weight ratio reaches 7.7%, which is much superior to the ratio 15–25% of minisatellites (satellites with the weight in the range from 100 to 500 kg) made of traditional aluminum honeycomb sandwich panels. When this satellite structure is submitted to a high-frequency loading whose amplitude is comparable to the real service condition, the unchanged eigen frequencies confirm that no structure degradation would take place during the testing. The advantages of present structures can be summarized as follows: 1) excellent stiffness-to-weight ratio property, 2) high strength at joint position with large concentrated force, 3) small amount of structural connections, and 4) the fabrication cycle is quite short because of avoiding the bonding process between face sheets and core as well as the structural inserts embedding process.

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References


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